

THE UNIVERSITY OF WESTERN AUSTRALIA

FIRST SEMESTER EXAMINATIONS

June 1998

**Computer Vision 412**

233.412

This paper contains:

7 questions;

6 pages.

Time allowed: 2 hours

Reading time: 10 minutes

Each question is worth 10 marks.

All third year candidates should attempt SIX questions.

All fourth year candidates must attempt ALL Questions.

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1.

- (a) Explain the difference between 4-connectedness and 8-connectedness. (2)
- (b) State the Jordan Curve Theorem. (1)
- (c) Give an example of a simple binary image that violates the Jordan Curve Theorem under both 4-connectedness and 8-connectedness. Explain the violations. (3)
- (d) Outline the sequential scan labelling algorithm for labelling connected components in a binary image. Assume 6-connectedness. (4)
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2.

- (a) A mean filter is a linear filter, but a median filter is not. Why? (2)
- (b) Compare the characteristics of mean and median filters and identify the situations where you would use them. (2)
- (c) An  $8 \times 8$  image  $f(i, j)$  has grey levels given by the following equation:

$$f(i, j) = |i - j|, \text{ for } i, j = 0, \dots, 7.$$

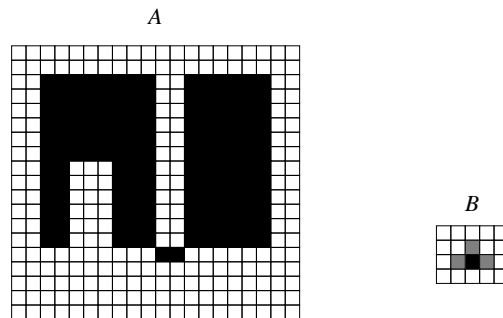
Find the output image obtained by applying a  $3 \times 3$  median filter on the image  $f(i, j)$ ; note that the border pixels remain unchanged.

(6)

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3.

- (a) Define the *dilation* and *erosion* of an object  $A$  by a structuring element  $B$ . (2)
- (b) Sketch the dilation and erosion of the object labelled  $A$  in the figure below, using the structuring element shown. Note that the centre of the binary structuring element  $B$  is given by the darker pixel.



- (4)
- (c) What does it mean to say that “dilation and erosion are duals to each other with respect to set complementation and reflection”? Express this mathematically. (2)
- (d) Define the *opening* of  $A$  by  $B$ , and the *closing* of  $A$  by  $B$ . (2)

4.

- (a) Explain what a difference-of-Gaussians filter is and why one would convolve an image with such a filter. (3)
- (b) State the Convolution Theorem for Fourier transforms. (2)
- (c) Sketch the shape of the Fourier transform of a difference-of-Gaussians filter, and explain how you derived this shape. Is it a low-pass, band-pass, or high-pass filter? (5)
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5.

- (a) Explain the difference between the image motion field and the optical flow. Give an example where these two differ. (2)
- (b) Consider a point object located at *world* coordinates  $(10, 0, 10)$  at time  $t = 0$ . A camera system with a focal length of 2 is located such that its *lens centre* is at the origin of the world coordinate system and its optical axis is looking directly at the object at time  $t = 0$ . The object is moving with a uniform velocity of  $(5, 0, 0)$ .
- (i) What are the coordinates of the point object in the image plane at time  $t = 0$ ?
- (ii) Find the image coordinates of the point at time  $t = 1$  if
- A. The camera is stationary.
- B. The camera translates with a uniform velocity of  $(0, 0, 5)$ .
- (8)
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6.

(a) Draw a diagram showing a single world point  $W = (X, Y, Z)$  imaged by two perfectly aligned identical cameras, with focal length  $f$ , and lens centres separated by a distance  $b$ . Assume the world coordinates  $(X, Y, Z)$  are measured with respect to a coordinate frame attached to the focal point of the left camera.

(2)

(b) Write down the relationships between  $X$  and the image  $x$ -coordinates,  $x_l$  and  $x_r$  in the left and right images.

(2)

(c) Show how these expressions may be used to solve for  $Z$  given the coordinates of the image of  $W$  in each camera.

(2)

(d) Draw a diagram showing the geometry of a structured lighting arrangement, where the camera and the projector are offset by a baseline distance  $b$ , and the projector is at an angle  $\theta$  with respect to the optical axis of the camera.

(2)

(e) What is the equation that relates the world point coordinates  $(X, Y, Z)$  to the image coordinates  $(x, y)$ ?

(2)

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7.

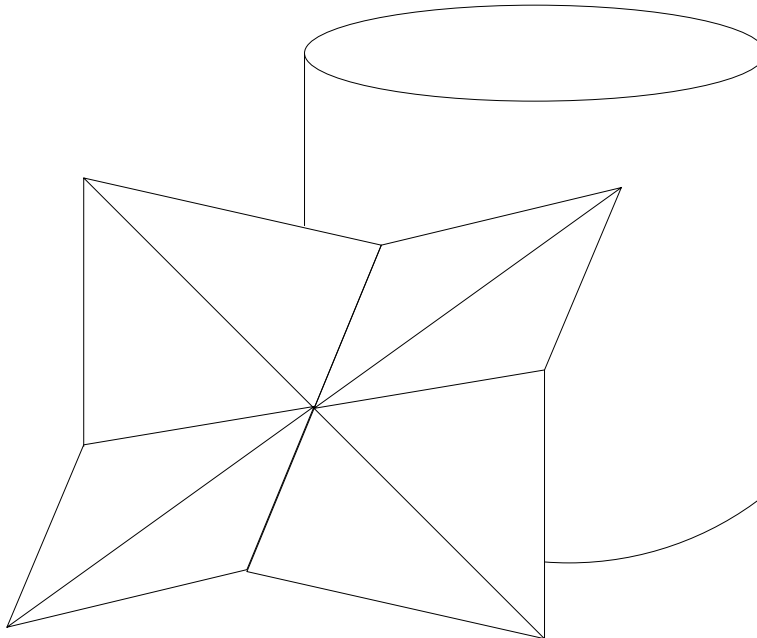
- (a) Explain the difference between an illumination discontinuity, an orientation discontinuity, a depth discontinuity, and a surface reflectance discontinuity. Draw a diagram illustrating each of these discontinuities.

(5)

- (b) List the six possible edge labels and the four possible junction types.

(2)

- (c) Provide a valid labelling the following edge drawing:



(2)

- (d) What geometrical event does a T-junction signify?

(1)